



Cross-platform Software Optimization with Intel's Ct Technology

Software AND Services

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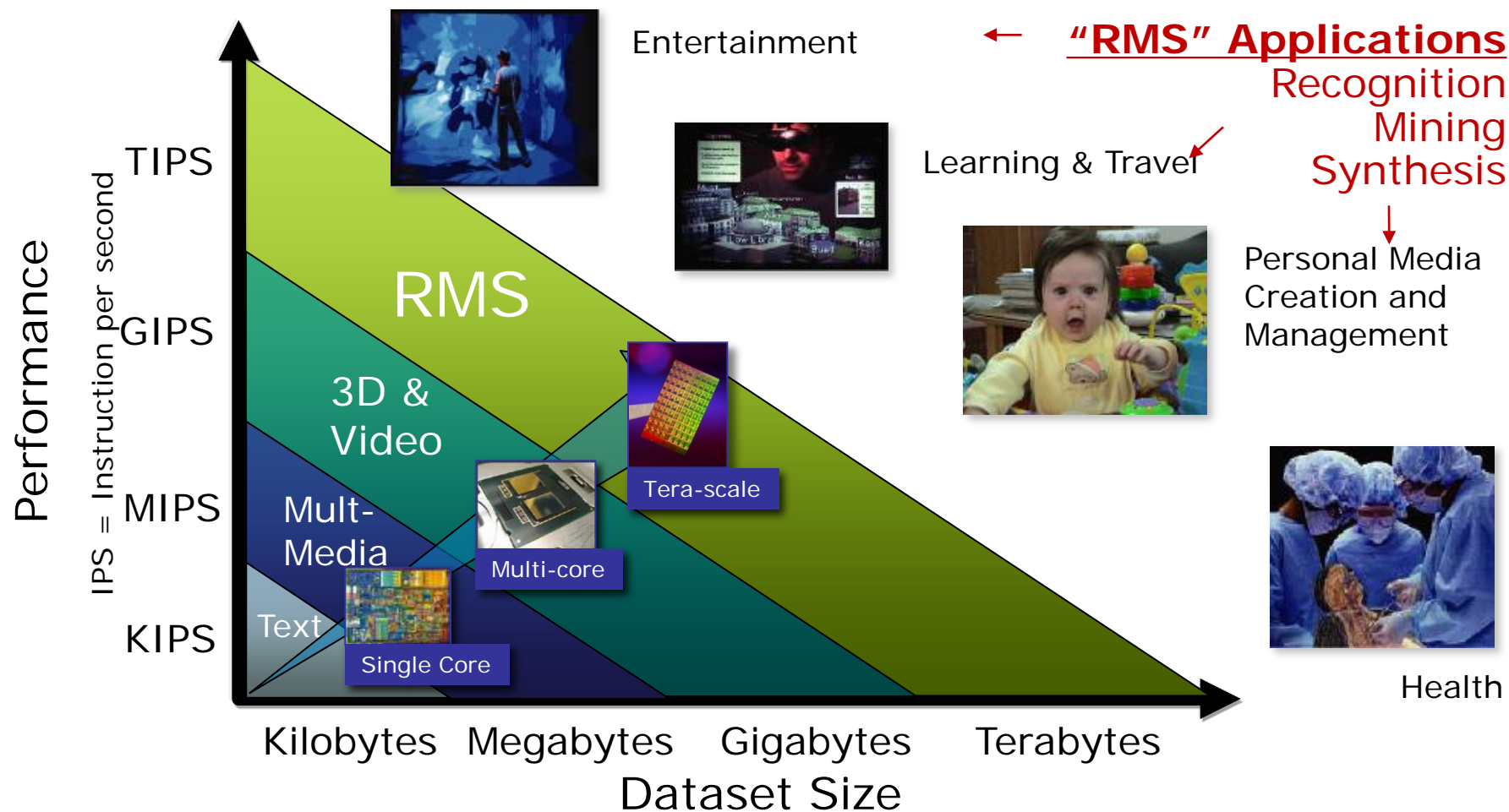
Agenda

- **What is Intel's Ct Technology?**
- **How does Intel's Ct Technology work?**
- **How to port C++ code to Intel's Ct Technology?**

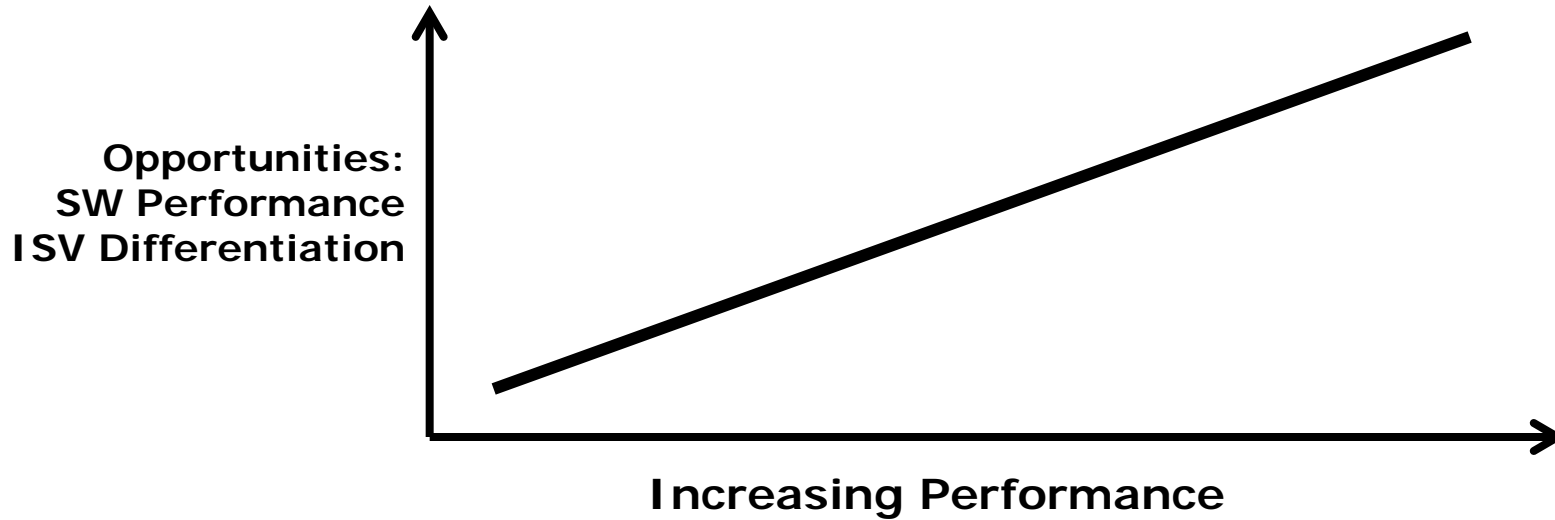


What is Intel's Ct Technology?

Throughput and Visual Computing Applications



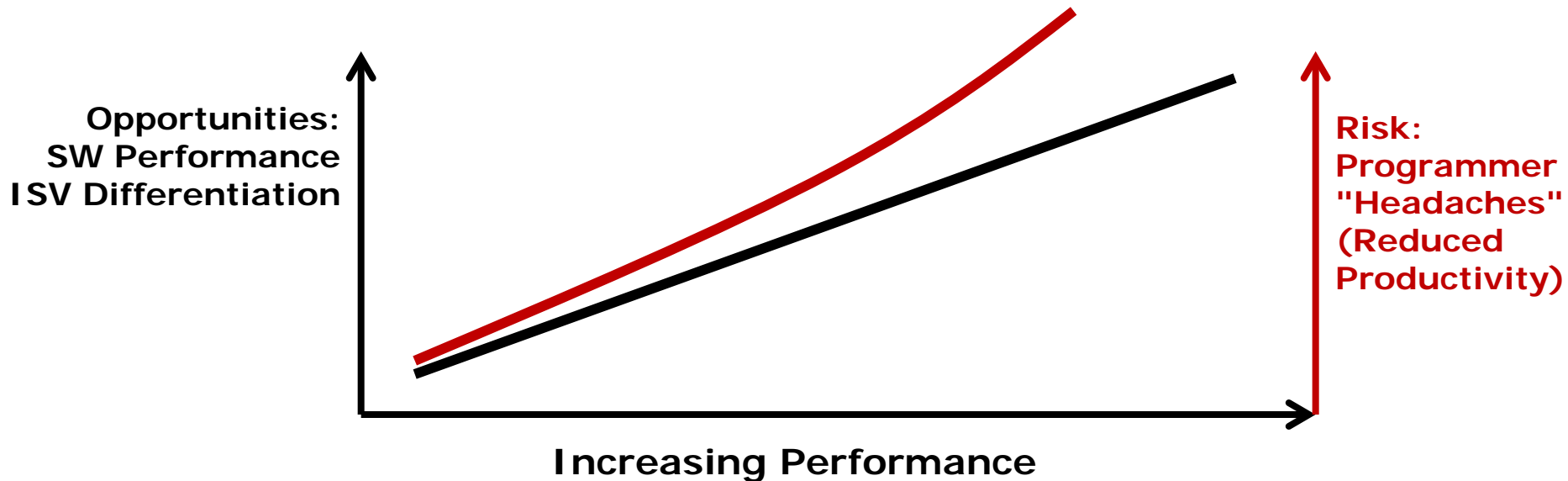
Software Opportunities and Risks



Many-core architecture offers unprecedented opportunities for differentiation:

- **Model-based applications:** New functionalities enriching the user's experience
- **Improved quality:** Higher resolution/accuracy in results
- **Increased usability:** Raw power to fuel more sophisticated usage models

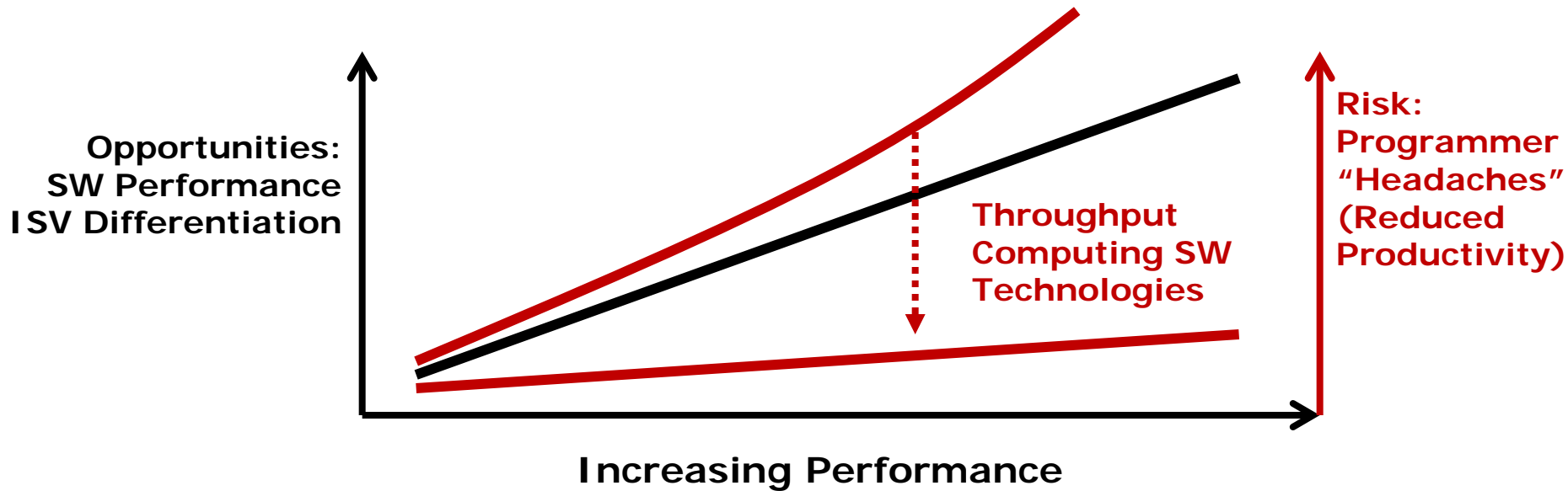
Software Opportunities and Risks



Reduced Productivity:

- **Data races:** New class of bugs that increase exponentially with degree of parallelism
- **Performance tuning:** Programmers can expect to spend most time here
- **Forward scaling:** Anticipating future HW enhancements
- **Modularity:** Difficult to compose parallel programs
- **Proprietary Tools:** Reduces choice and challenges build infrastructure

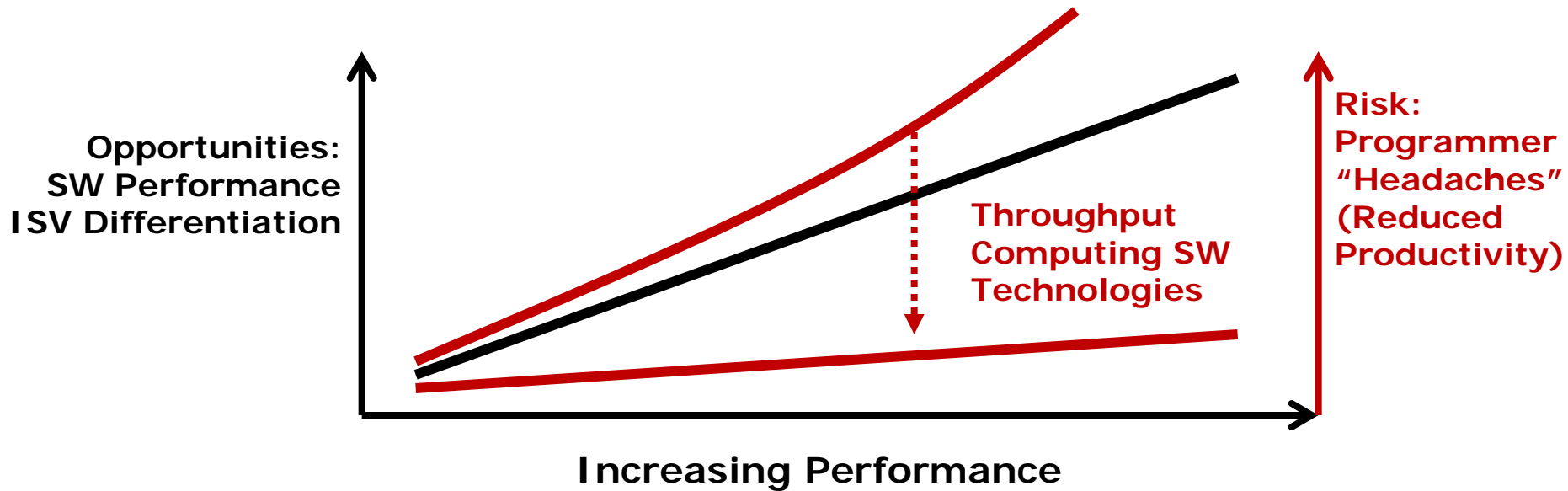
Software Opportunities and Risks



Visual computing software technologies make it easier:

- **Industry Standard APIs:** DirectX*, OpenGL*
- **Native Tools:** SSE/AVX/Co-processor Native Compilers, OpenMP*, Intel® Threading Building Blocks, etc.
- **New Tools**, including:
 - *Ct - Forward-scaling, easy-to-use, and deterministic*

Software Opportunities and Risks

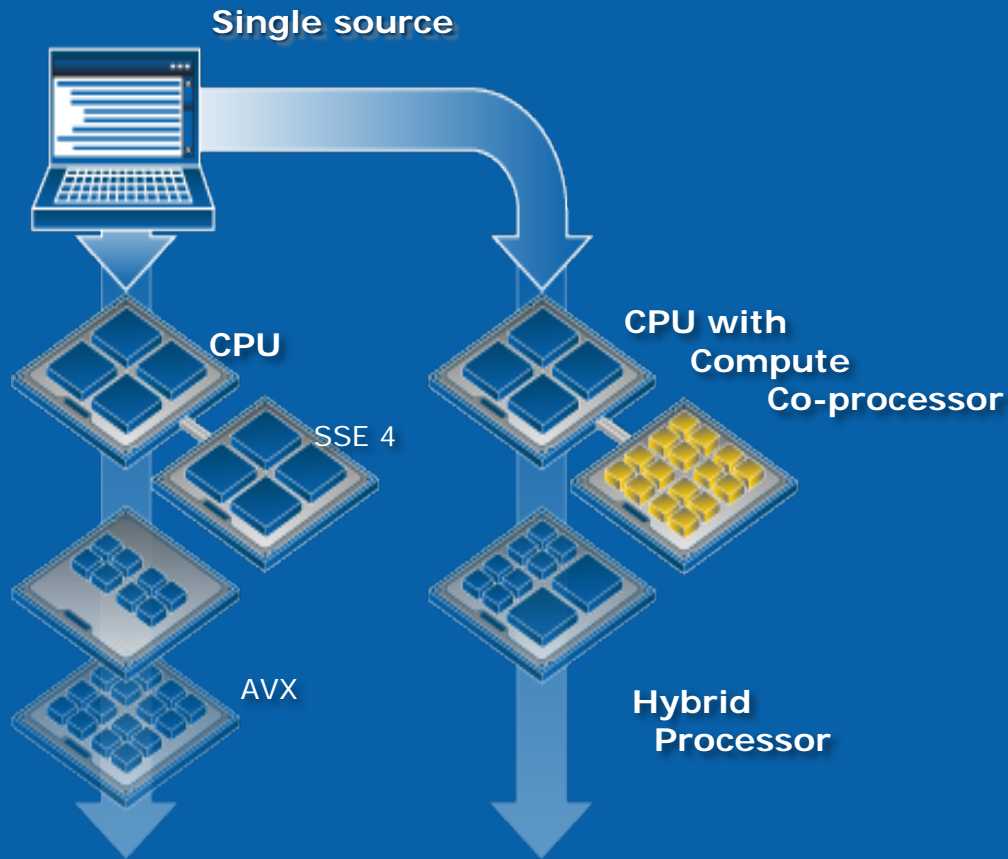


Productivity is greatly increased with the right choice of tools

Intel's Ct Technology

- **Productive Data Parallel Programming**
 - Presented as high-level abstraction, natural notation
 - Delivers application performance with ease of programming
- **Ct forward-scales software written today**
 - Ct is designed to be dynamically retargetable to SSE, AVX, co-processor, and beyond
- **Extends standard C++ using templates**
 - No changes to standard C++ compilers
- **Ct abstracts away architectural details**
 - Vector ISA width / Core count / Memory model / Cache sizes
- **Ct is deterministic**
 - No data races

Forward Scaling with Ct



Productivity

- Integrates with existing tools
- Applicable to many problem domains
- Safe by default: maintainable

Performance

- Efficient and scalable
- Harnesses both vectors and threads
- Eliminates modularity overhead of C++

Portability

- High-level abstraction
- Hardware independent
- Forward scaling

What Does the Product Based on Intel Ct Technology Look Like?

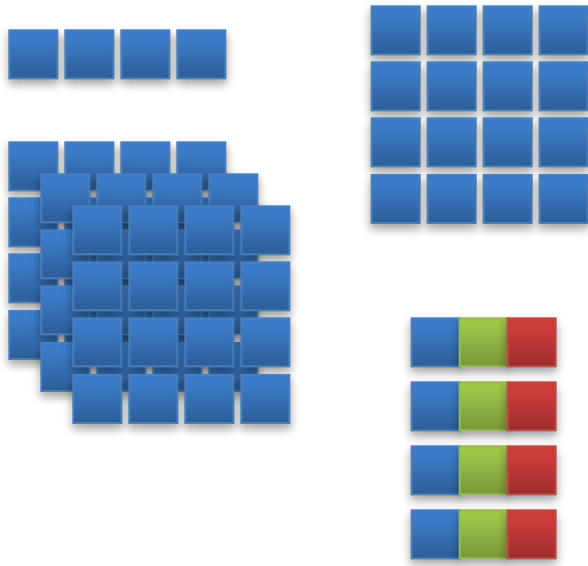
- Core API
 - Flexible, forward scaling data parallelism in C++
- Application Libraries
 - Linear Algebra, FFT, Random Number Generation
 - Powered by Intel® Math Kernel Library (Intel® MKL)!
- Samples
 - Medical Imaging, Financial Analytics, Seismic Processing, and more
- Initial release on Windows, followed by Linux*
 - IA-32 and Intel® 64
 - Works with Intel® C/C++ Compiler, Microsoft* Visual C++*, and GCC*
 - Works with Intel® VTune™ Analyzer



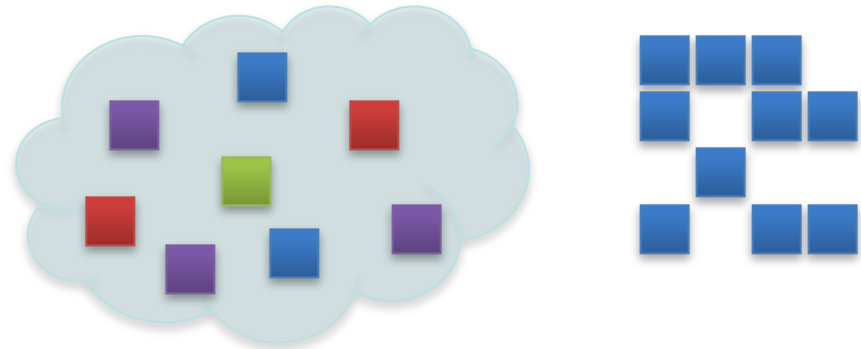
How does Intel's Ct Technology work?

Ct's Parallel Collections

Regular dense containers



Irregular dense containers



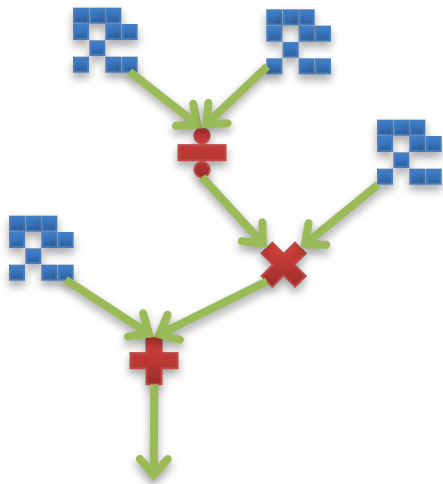
& growing...

- Ct operates on data collections called containers
 - Based on C++ templates
- Ct's containers represent a variety of regular and irregular data collections
 - `dense<T>`, `dense<T,2>`, `dense<T,3>`, `nested<T>`, `indexed <T>`

Expressing Computation in Ct

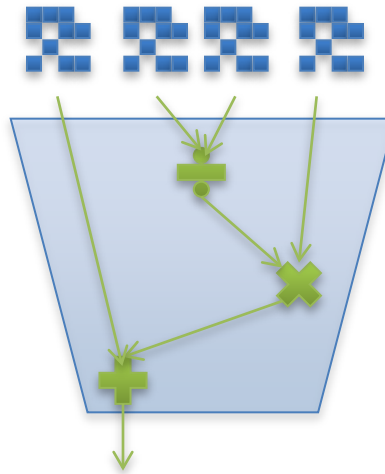
The Ct JIT Automates This Transformation

Vector Processing



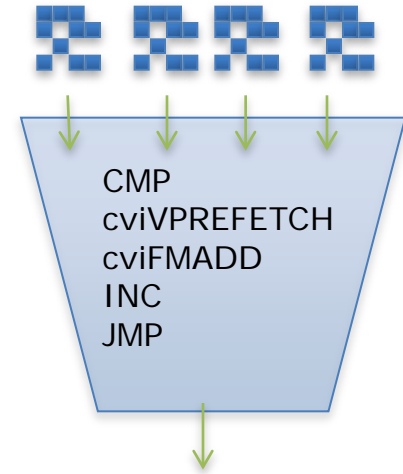
```
dense<f32> A, B, C, D;  
A += B/C * D;
```

Scalar Processing



```
f32 kernel(f32 a, b, c, d) {  
    return a + (b/c)*d;  
}  
...  
dense <f32> A, B, C, D;  
A = map(kernel)(A, B, C, D);
```

Native/Intrinsic Coding



```
native(ndense<f32> a, b, c, d) {  
    __asm__ {  
        ...  
    }  
}  
...  
ndense<f32> A, B, C, D;  
A = nmap(native)(A, B, C, D);
```

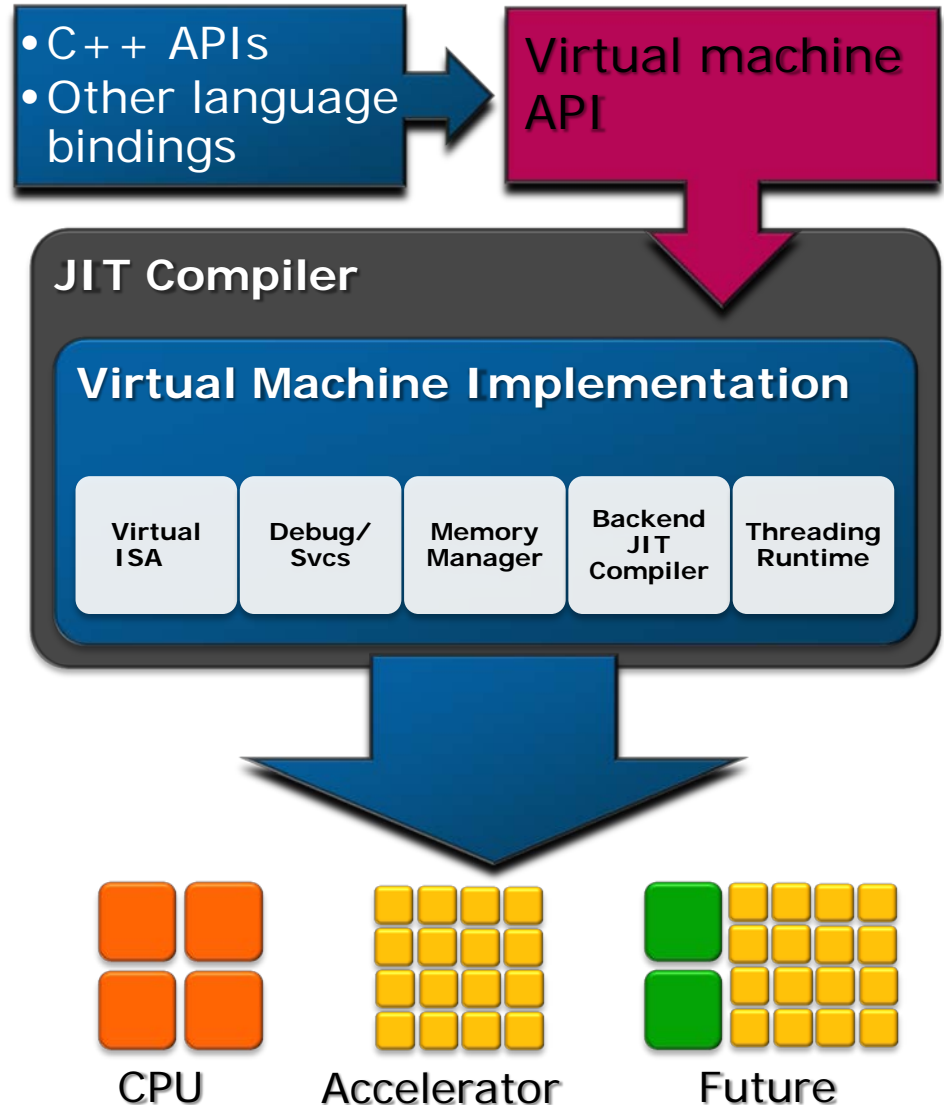
Or Programmers Can Choose Desired Level of Abstraction

The Ct Runtime

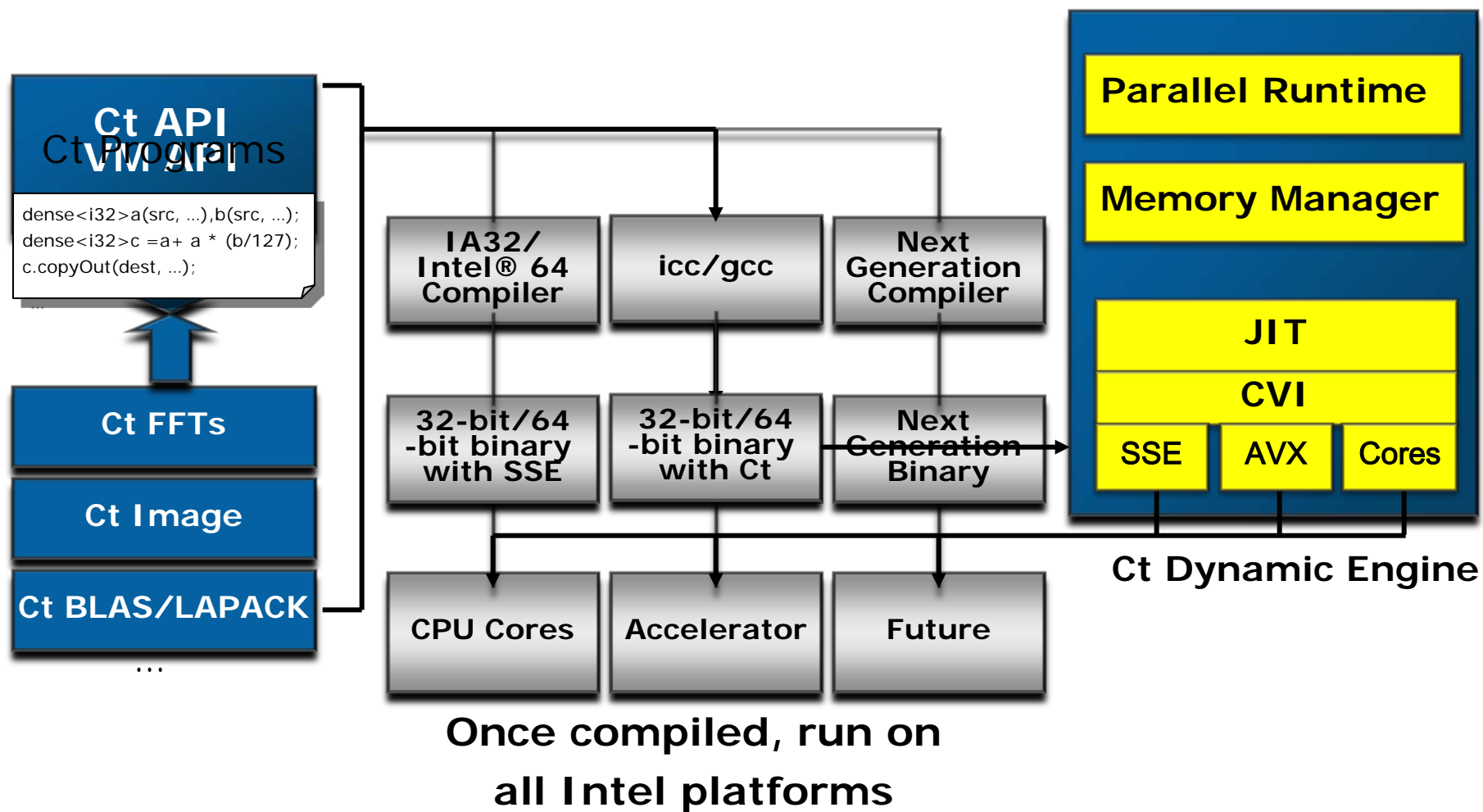
- Intel Ct Technology offers a standards compliant C++ library...

...backed by a runtime


- Runtime generates and manages threads and vector code, via
 - Machine independent optimization
 - Offload management
 - Machine specific code generation and optimizations
 - Scalable threading runtime (based on Intel® Threading Building Blocks)



Dynamic Ct: Supporting All Intel Platforms



Ct Dynamic Engine Execution



```
int ar_a[1024], ar_b[1024]
```

```
dense<i32> A(ar_a, ...);
```

```
dense<i32> B(ar_b,...);
```

```
call( work ) ( A, B );
```

Ct Dynamic
Engine



Ct Dynamic Engine Execution

```
int ar_a[1024], ar_b[1024]
```

```
dense<i32> A(ar_a, ...);
```

```
dense<i32> B(ar_b,...);
```

```
call( work ) ( A, B );
```

Ct Dynamic
Engine

Memory Manager

a 

b 

Ct Dynamic Engine Execution

```
int ar_a[1024], ar_b[1024]
```

```
dense<i32> A(ar_a, ...);
```

```
dense<i32> B(ar_b,...);
```

```
call( work ) ( A, B );
```



```
void work(dense<i32> a,  
          dense<i32> & b )
```

```
{
```

```
    b = a + 1;
```

```
}
```

Ct Dynamic
Engine

IR Builder

Memory Manager

a 

b 

Ct Dynamic Engine Execution

```
int ar_a[1024], ar_b[1024]
```

```
dense<i32> A(ar_a, ...);
```

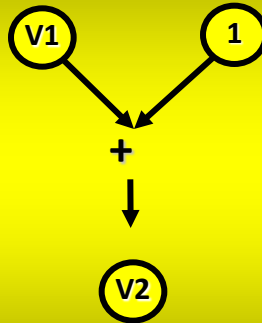
```
dense<i32> B(ar_b,...);
```

```
call( work ) ( A, B );
```

```
void work(dense<i32> a,  
          dense<i32>& b )  
{  
    b = a + 1;  
}
```

Ct Dynamic
Engine

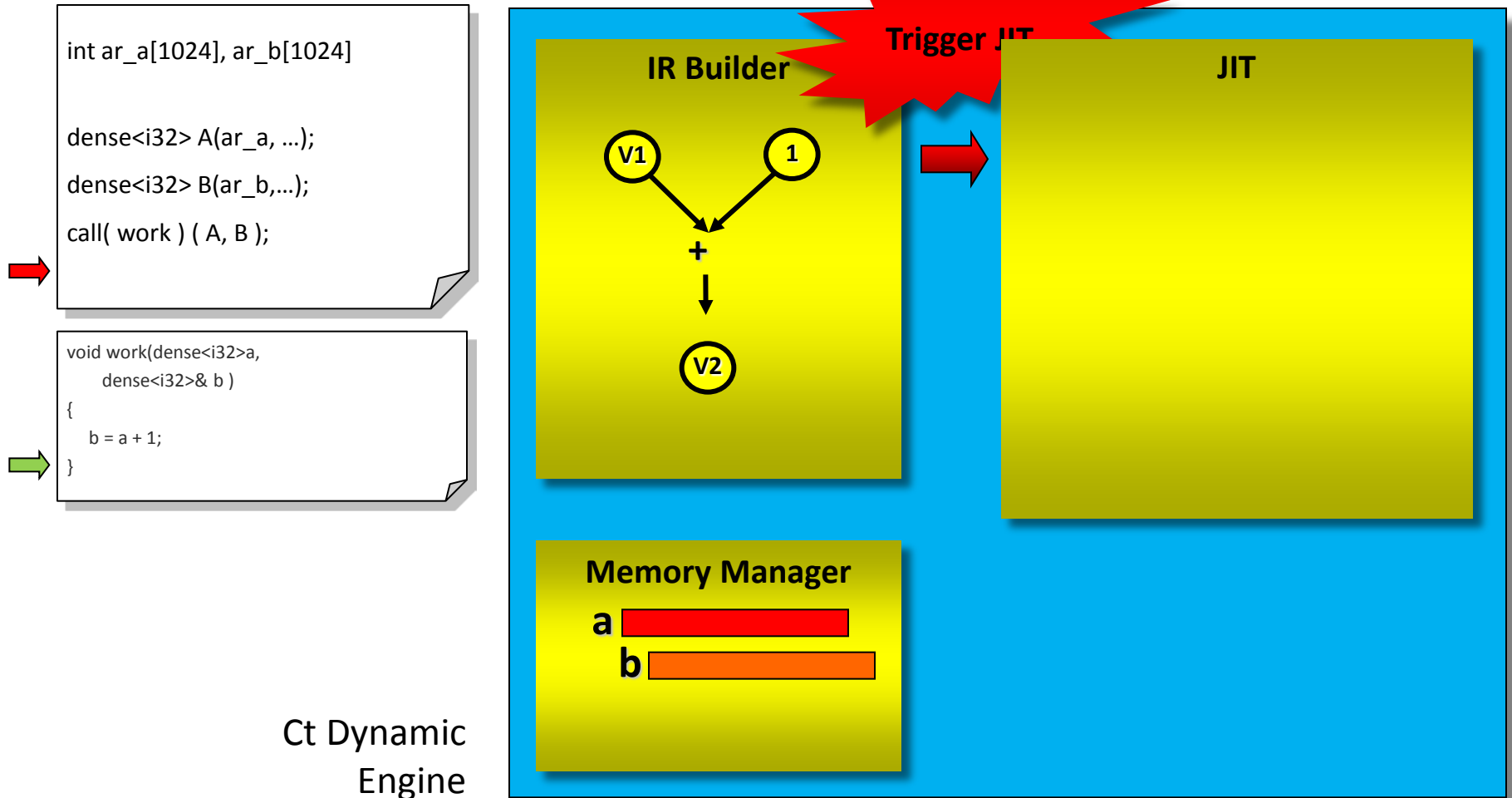
IR Builder



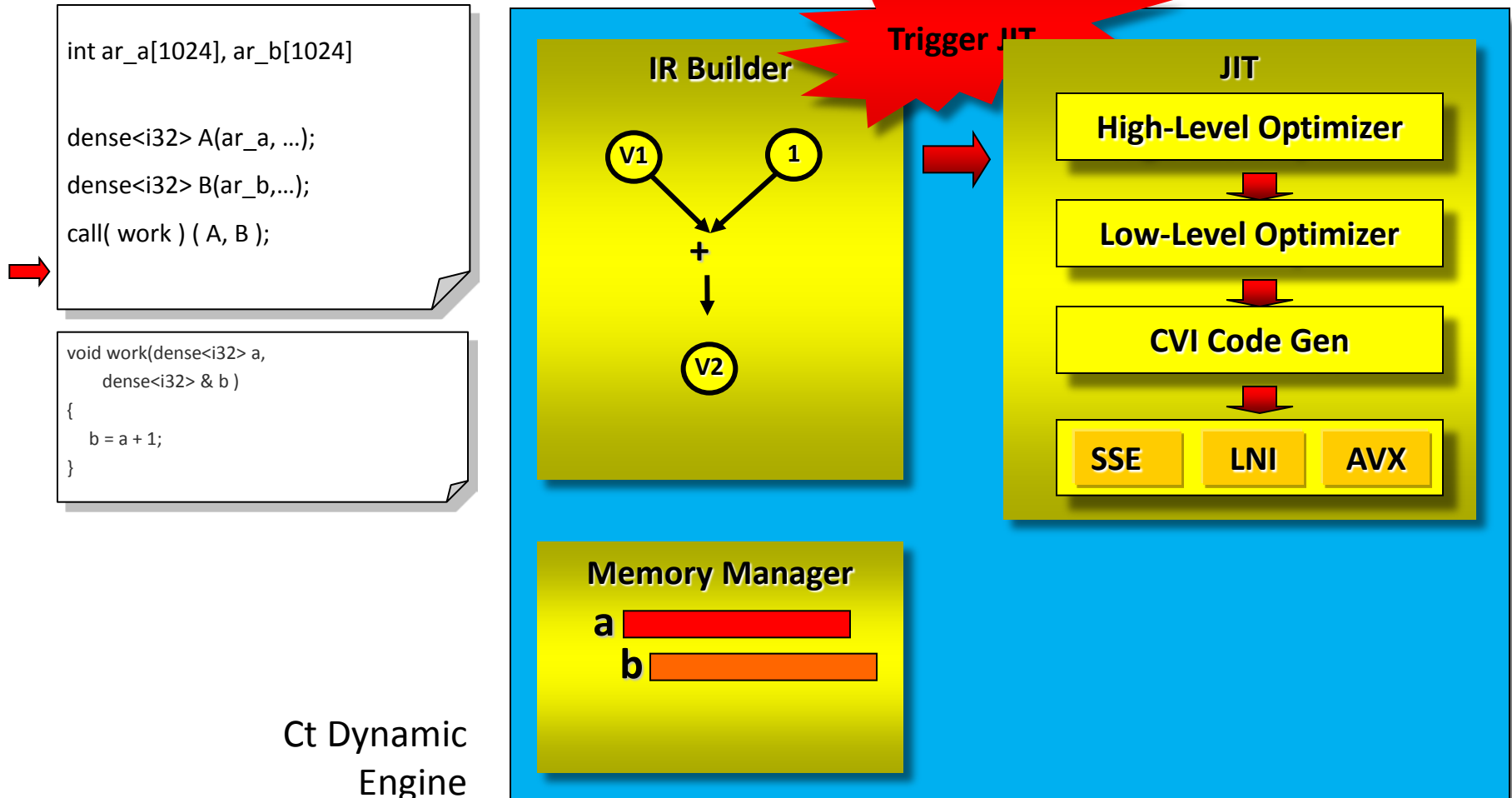
Memory Manager



Ct Dynamic Engine Execution



Ct Dynamic Engine Execution



Ct Dynamic Engine Execution

```
int ar_a[1024], ar_b[1024]
```

```
dense<i32> A(ar_a, ...);
```

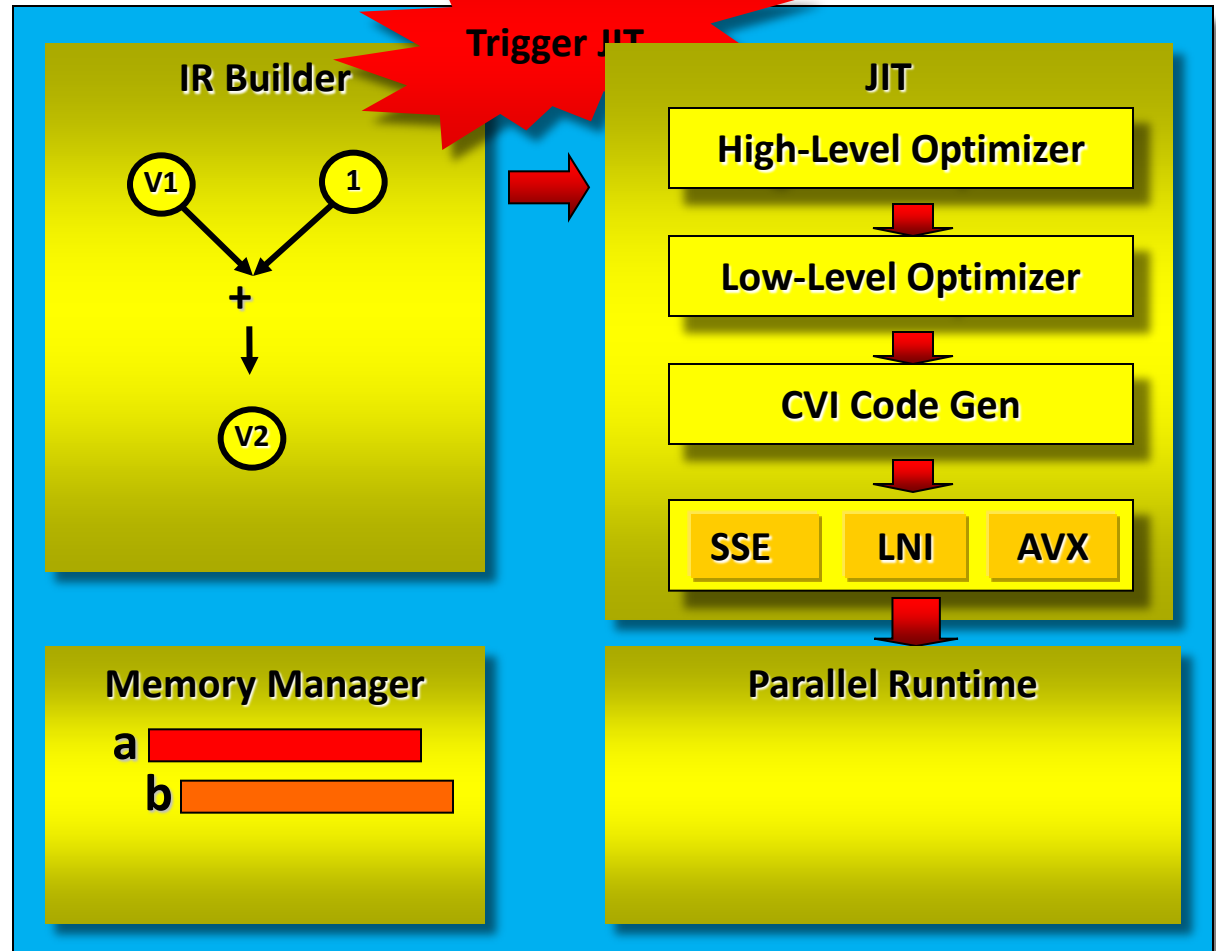
```
dense<i32> B(ar_b,...);
```

```
call( work ) ( A, B );
```

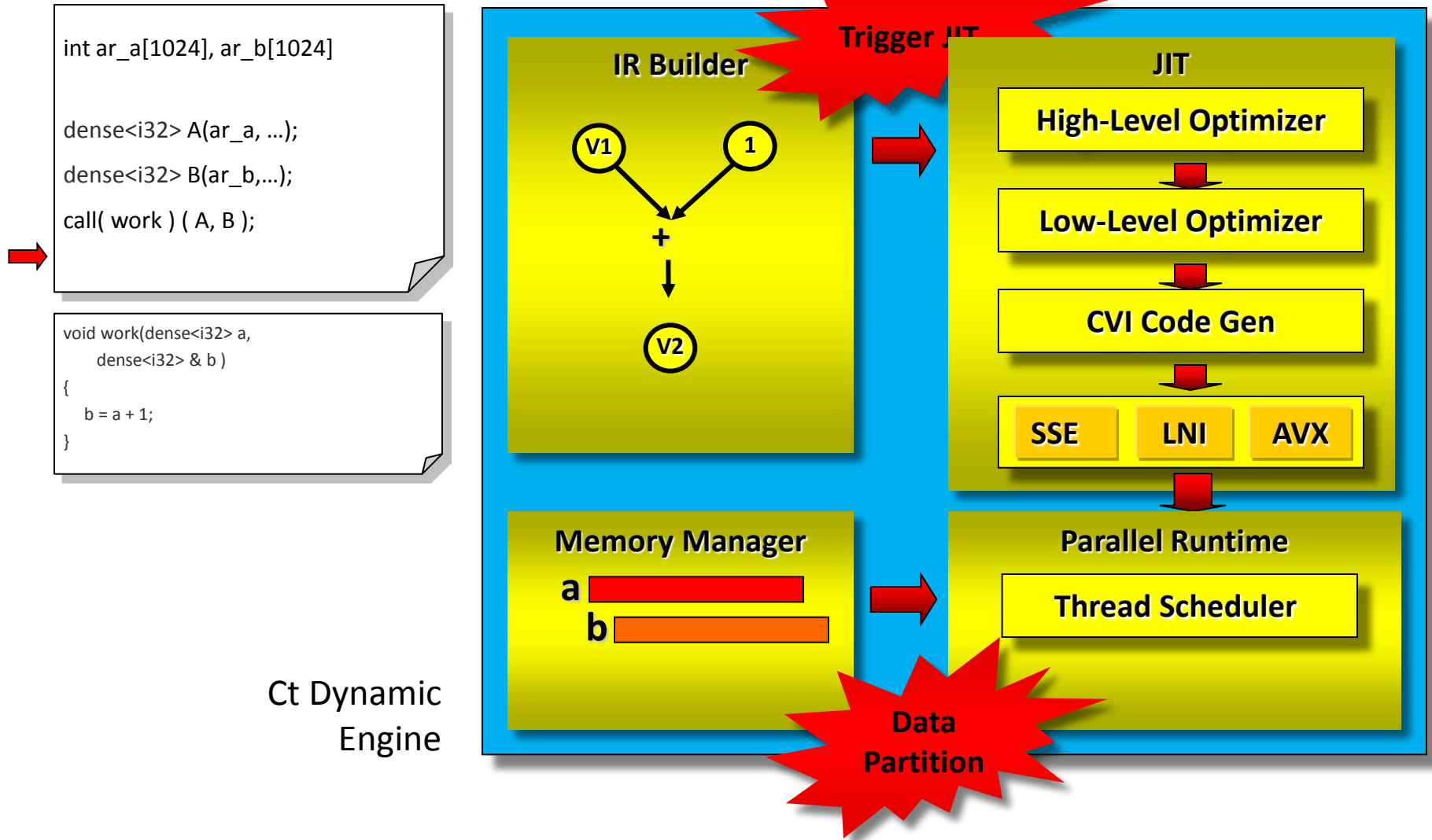
```
void work(dense<i32> a,  
         dense<i32> & b )  
{  
    b = a + 1;  
}
```

```
    b = a + 1;
```

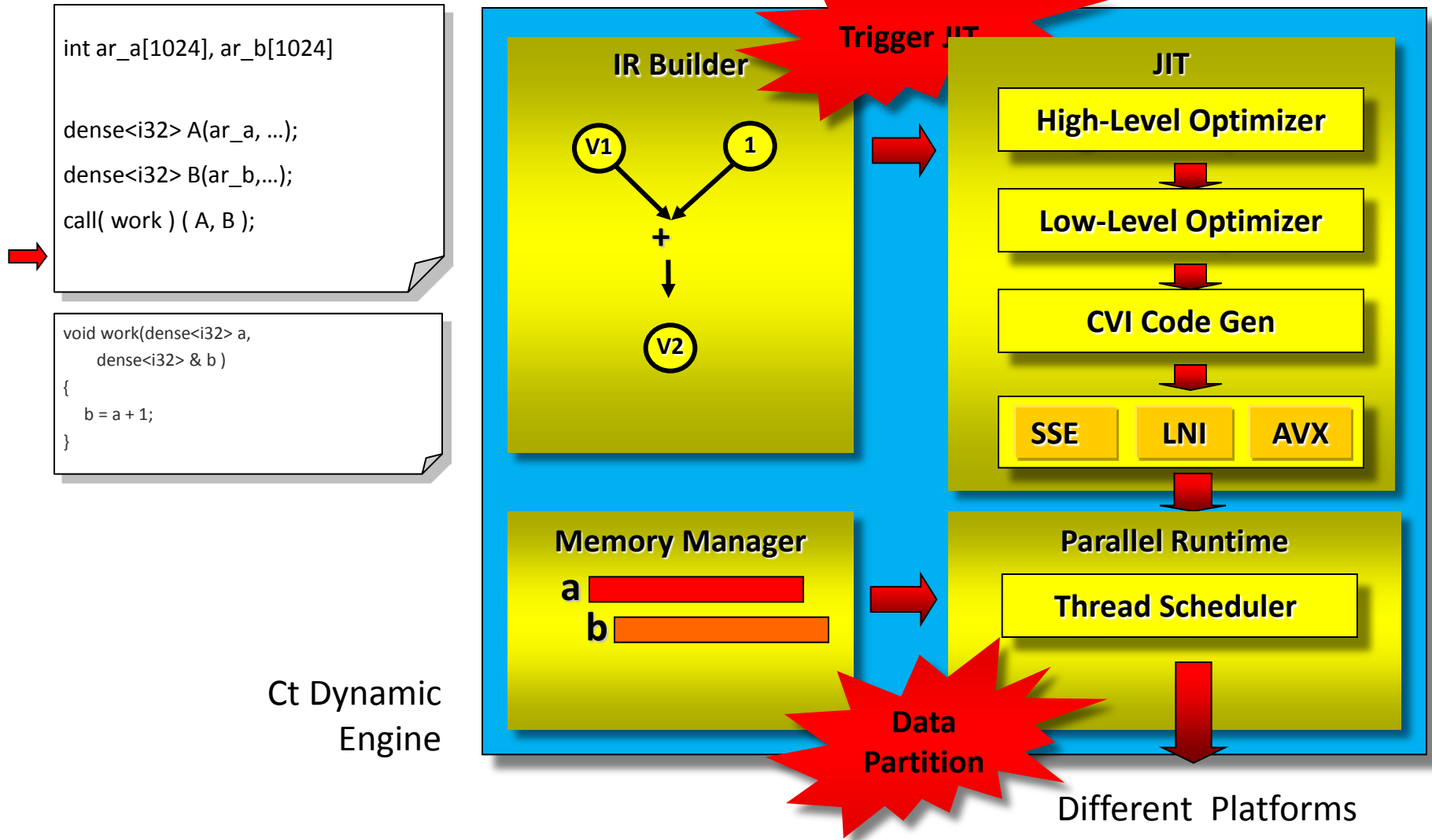
Ct Dynamic
Engine



Ct Dynamic Engine Execution



Ct Dynamic Engine Execution



Ct Dynamic Engine Execution

```
int ar_a[1024], ar_b[1024]
```

```
dense<i32> A(ar_a, ...);
```

```
dense<i32> B(ar_b,...);
```

```
call( work ) ( A, B );
```



**Compute
Kernel
Again**

Ct Dynamic
Engine

Code Manager

Emitted Code for 'work'



Memory Manager

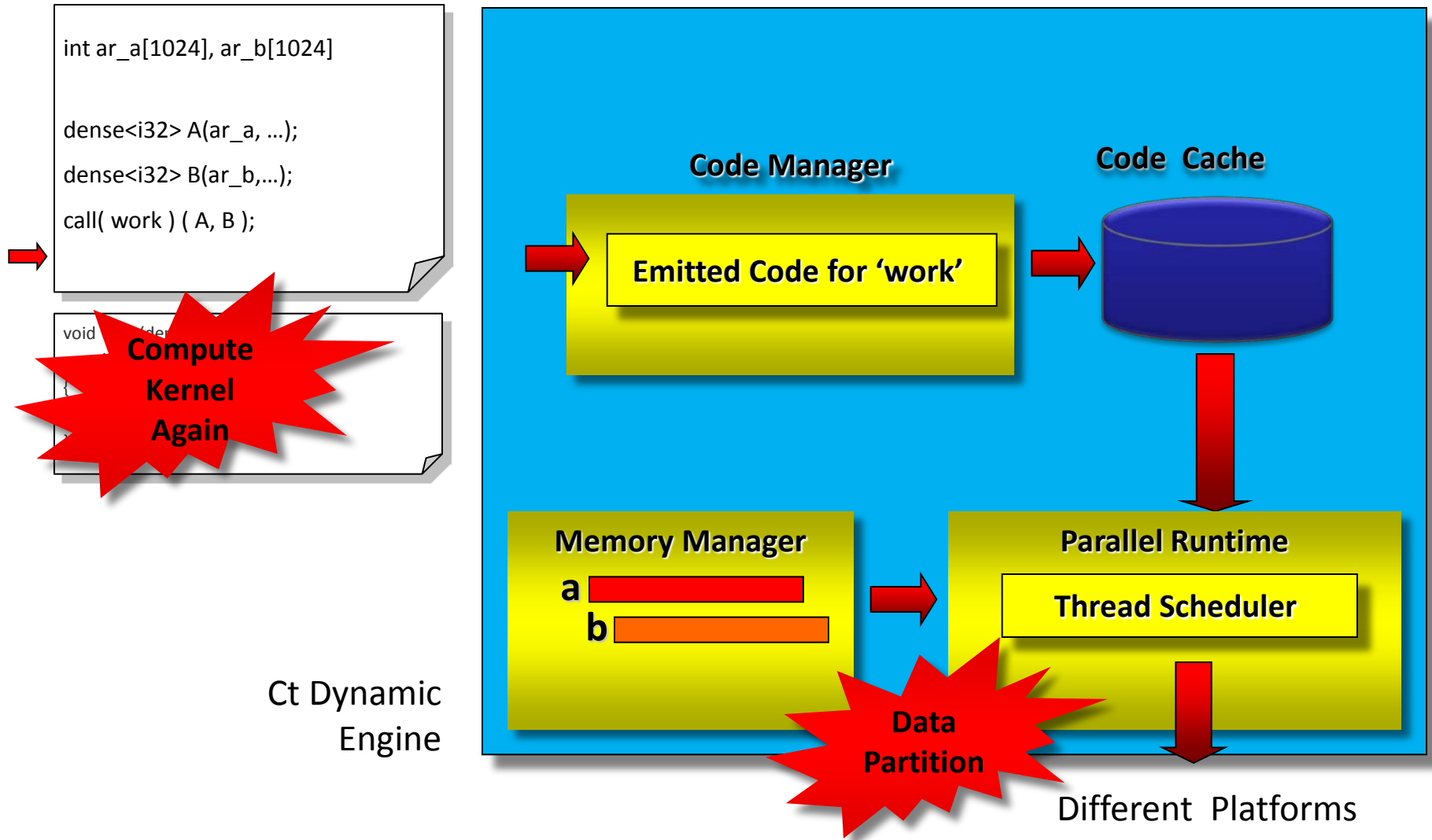
a 

b 

Parallel Runtime

Thread Scheduler

Ct Dynamic Engine Execution



Ct Dynamic Engine Implications

- **Second stage of compilation at runtime**
Allows run-time specialization
- **Ct kernel: exists as C function, but**
 - Executes only once => for dynamic compilation
 - Symbolic “capture” of computation
 - Takes a snapshot of current bindings and state
- **Ct call: execution is a remote function call**
 - Data flow dependencies inferred
 - Automatic (and always safe) synchronization
 - Enables remote execution and data storage

Why Does this Matter?

Widely used libraries often give up performance for well designed generic interfaces and modularity

- Virtual function calls, function pointers, and control flow dependent on parameters not known until runtime can limit performance
- Modularity inherently spreads computation across methods
- In extreme cases, the application is effectively an interpreter for a computation specified at runtime

→ *Dynamic compilation can “compile out” the overhead of such “late binding”*

→ *This advantage is MULTIPLICATIVE with parallelism*



**How to port C++ code to
Intel's Ct Technology?**

Ct Programming Common Steps

- Identify the computation logic to be written in Ct
- Figure out the signature of the kernel
- Prepare C data buffer for input/output
- Set up C => Ct kernel bridge by rcall
- Implement kernel

Step 1: Figure Out Kernel Signature

```
int ar_a[1024];
int ar_b[1024];
...
...
...
...
for( i=0; i<1024; i++) {
    ar_b[i] = ar_a[i] + 1;
}
```

```
#include "ct.h"
using namespace Ct;
...
...
int ar_a[1024];
int ar_b[1024];
...
dense<i32> A( ar_a, 1024 );
dense<i32> B( ar_b, 1024 );
call( work ) ( A, B );
...
void work(dense<i32>a, dense<i32> &b){
    b = a + 1;
}
```


Step 2: Prepare Data

```
int ar_a[1024];  
int ar_b[1024];  
...  
...  
...  
...  
for( i=0; i<1024; i++) {  
    ar_b[i] = ar_a[i] + 1;  
}
```

```
#include "ct.h"  
using namespace Ct;  
...  
...  
int ar_a[1024];  
int ar_b[1024];  
...  
dense<i32> A( ar_a, 1024 );  
dense<i32> B( ar_b, 1024 );  
call( work ) ( A, B );  
...  
void work(dense<i32> a,dense<i32>&b ){  
    b = a + 1;  
}
```

Step 3: Set Up Bridge

```
int ar_a[1024];
int ar_b[1024];
...
...
...
...
for( i=0; i<1024; i++ ) {
    ar_b[i] = ar_a[i] + 1;
}
```

```
#include "ct.h"
using namespace Ct;
...
...
int ar_a[1024];
int ar_b[1024];
...
dense<i32> A( ar_a, 1024 );
dense<i32> B( ar_b, 1024 );
call( work ) ( A, B );
...
void work(dense<i32> a, dense<i32>&b ){
    b = a + 1;
}
```

Step 4: Implement Kernel

```
int ar_a[1024];  
int ar_b[1024];  
...  
...  
...  
...  
for( i=0; i<1024; i++) {  
    ar_b[i] = ar_a[i] + 1;  
}
```

```
#include "ct.h"  
using namespace Ct;  
...  
...  
int ar_a[1024];  
int ar_b[1024];  
...  
dense<i32> A( ar_a, 1024 );  
dense<i32> B( ar_b, 1024 );  
call( work ) ( A, B );  
...  
void work(dense<i32>a, dense<i32>&b ){  
    b = a + 1;  
}
```

Example: Black-Scholes for Options Pricing

Black-Scholes Using C Loops

```
float s[N], x[N], r[N], v[N], t[N];  
float result[N];  
for(int i = 0; i < N; i++)  
  
    float d1 = s[i] / ln(x[i]);  
    d1 += (r[i] + v[i] * v[i] * 0.5f) * t[i];  
    d1 /= sqrt(t[i]);  
    float d2 = d1 - sqrt(t[i]);  
  
    result[i] = x[i] * exp(r[i] * t[i]) *  
    ( 1.0f - CND(d2)) + (-s[i]) * (1.0f - CND(d1));  
}
```

Black-Scholes Using Ct

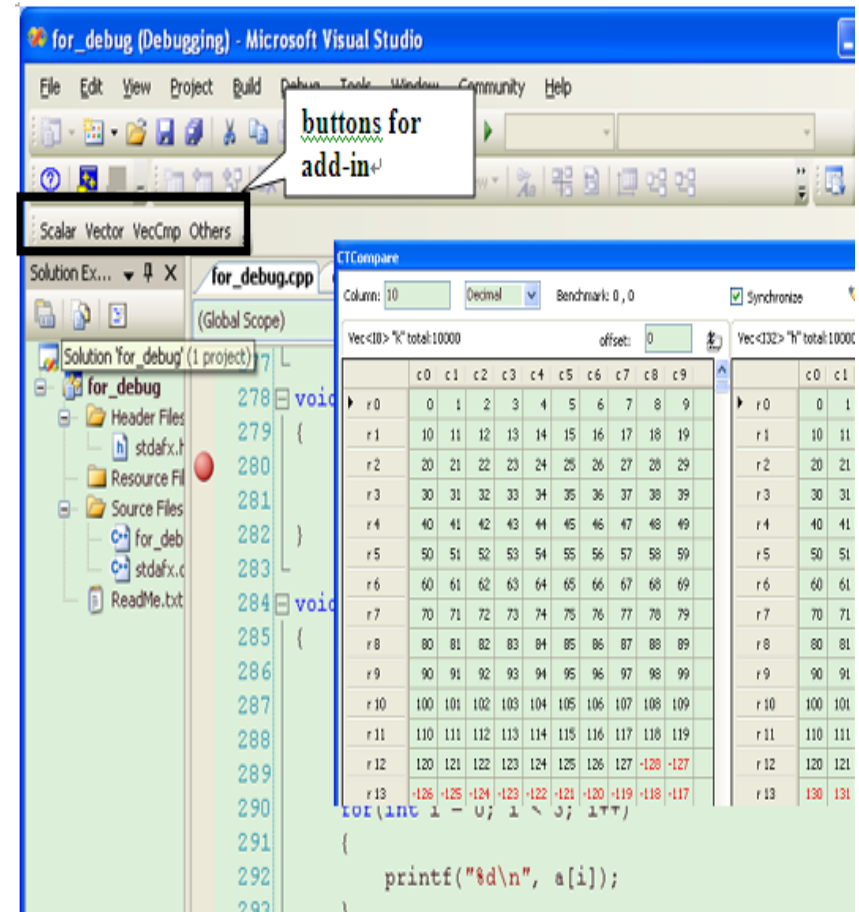
```
#include <ct.h>  
using namespace openCt;  
float s[N], x[N], r[N], v[N], t[N];  
float result[N];  
dense<f32> S(s, N), X(x, N), R(r, N), V(v, N), T(t, N);  
  
dense<f32> d1 = S / ln(X);  
d1 += (R + V * V * 0.5f) * T;  
d1 /= sqrt(T);  
dense<f32> d2 = d1 - sqrt(T);  
  
dense<f32> tmp = X * exp(R * T) *  
    ( 1.0f - CND(d2)) + (-S) * (1.0f - CND(d1));  
  
tmp.copyOut(result, sizeof(result));
```

- ① #include <ct.h> and using namespace
- ② Vector operations subsumes loop
- ③ The Ct code is almost the same as the original loop body
- ④ copyOut at the end (if you're done!)

Vector-style computation is a natural approach here.

Ct Debugging

- Link with the Emulation Library and debug with a C++ debugger
- Ct provides an Add-in to help watch Ct variables in Visual Studio*
- Dump the Intermediate Representation at various levels
- Use environments to control the Intermediate Representation level output level:
 - CT_DUMPJIT=y
 - HLO_TRACE_LEVEL =n
 - HLO_DISABLE_OPT=dump_cpp=f



CT Add-in in Visual Studio*

Summary

- Ct enables you to write simple parallel algorithms in standard C++
- Ct can get you performance on Intel Architecture today
- Ct Technology today will be forward-scalable to new many core and compute co-processors
- Ct will intermix with other parallel programming models and tools

Ct extends the many choices that Intel provides for Parallel Computing

Call to Action

Sign up for the opportunity to participate in Ct technology beta!

http://www.intel.com/software/data_parallel/

Additional sources of information on this topic:

- Visit our demo and talk to us at Booth #1116:
Medical imaging on deformable registration
- More web based information on Ct technology:
<http://software.intel.com/en-us/data-parallel/>
- Data parallelism whitepapers and tutorials:
<http://software.intel.com/en-us/articles/data-parallelism-whitepapers-and-tutorials/>

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